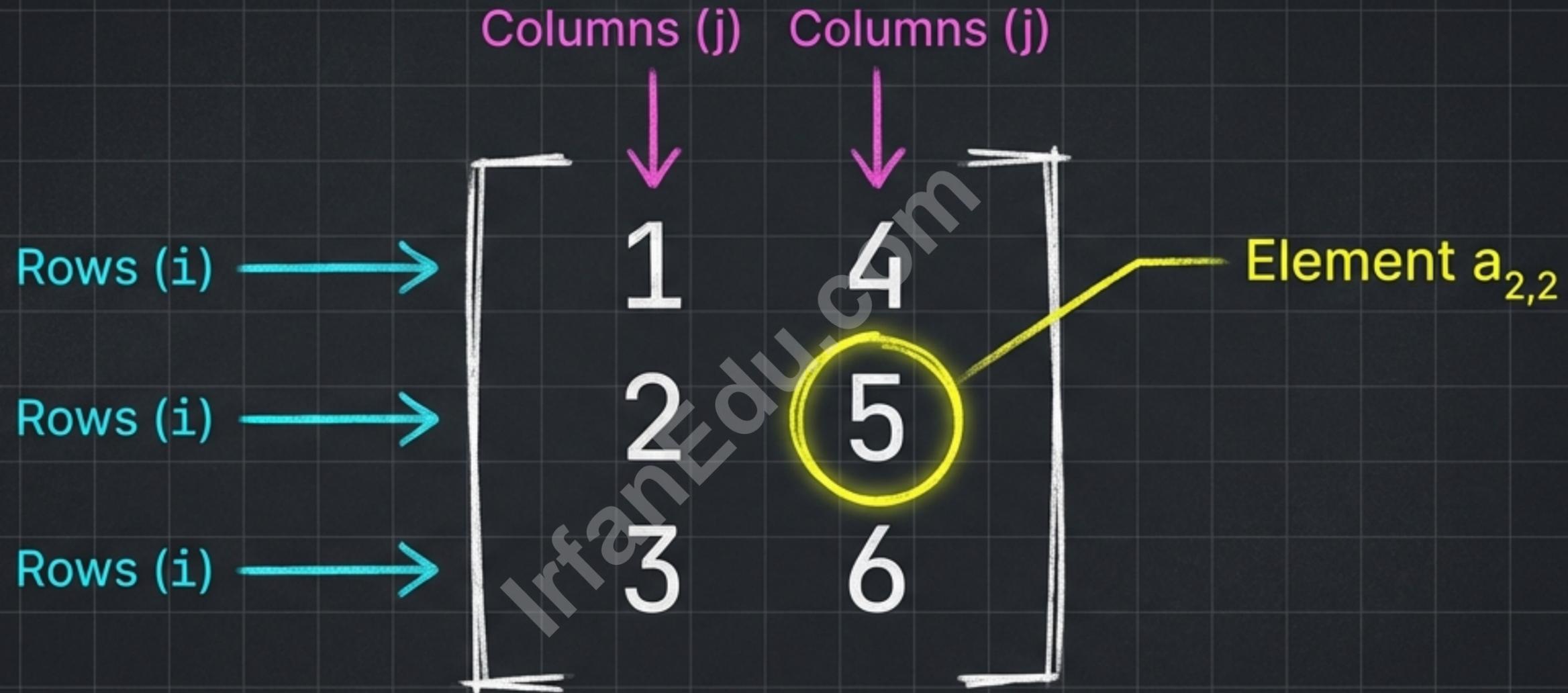


# FOUNDATIONS OF MATRIX ALGEBRA

Decoding the Grid: From Atomic  
Elements to Complex Systems

# THE ANATOMY OF A MATRIX



**Dimension = 3 Rows x 2 Columns**

*The address of any number is defined by row first, then column.*

# CLASSIFICATION BY STRUCTURE



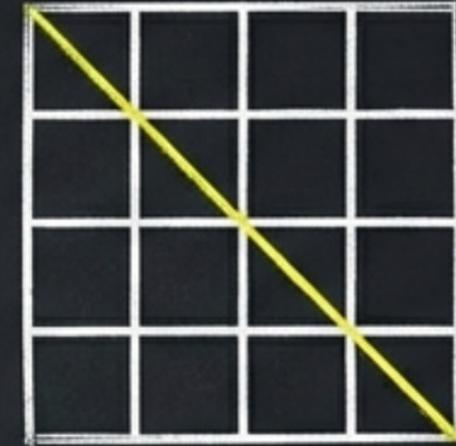
Row Matrix

$(1 \times 4)$



Column Matrix

$(4 \times 1)$



Square Matrix

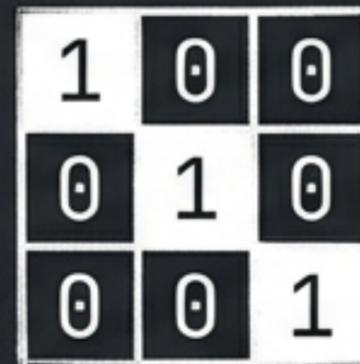
$(4 \times 4)$

— Main Diagonal



Diagonal Matrix

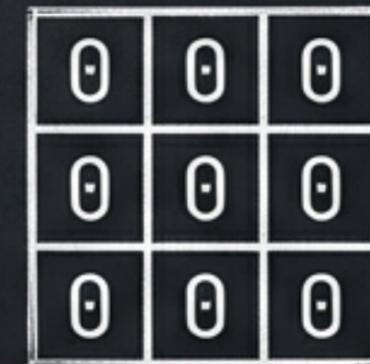
$(3 \times 3)$



Identity Matrix (I)

$(3 \times 3)$

The Multiplicative Identity



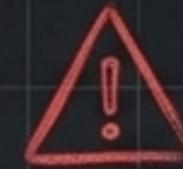
Zero Matrix (O)

$(3 \times 3)$

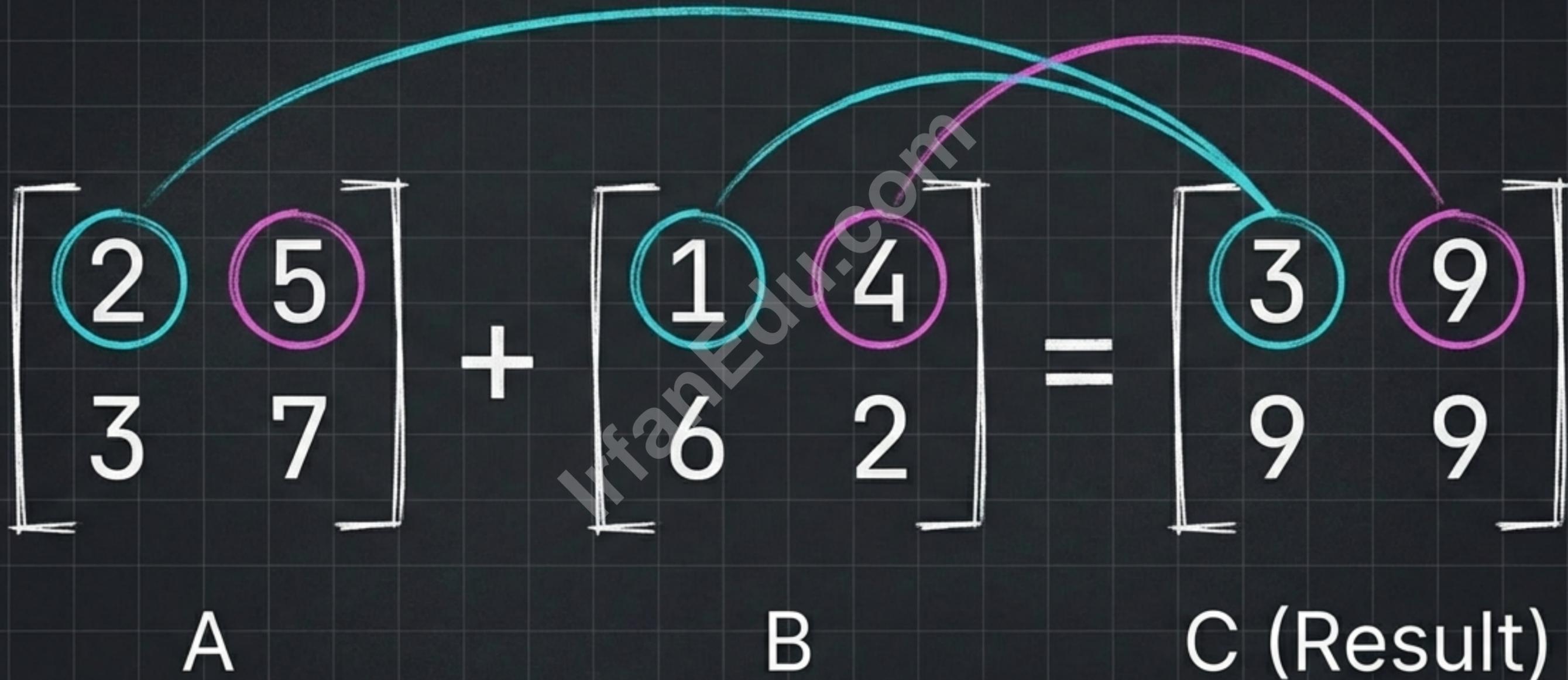
The Additive Identity

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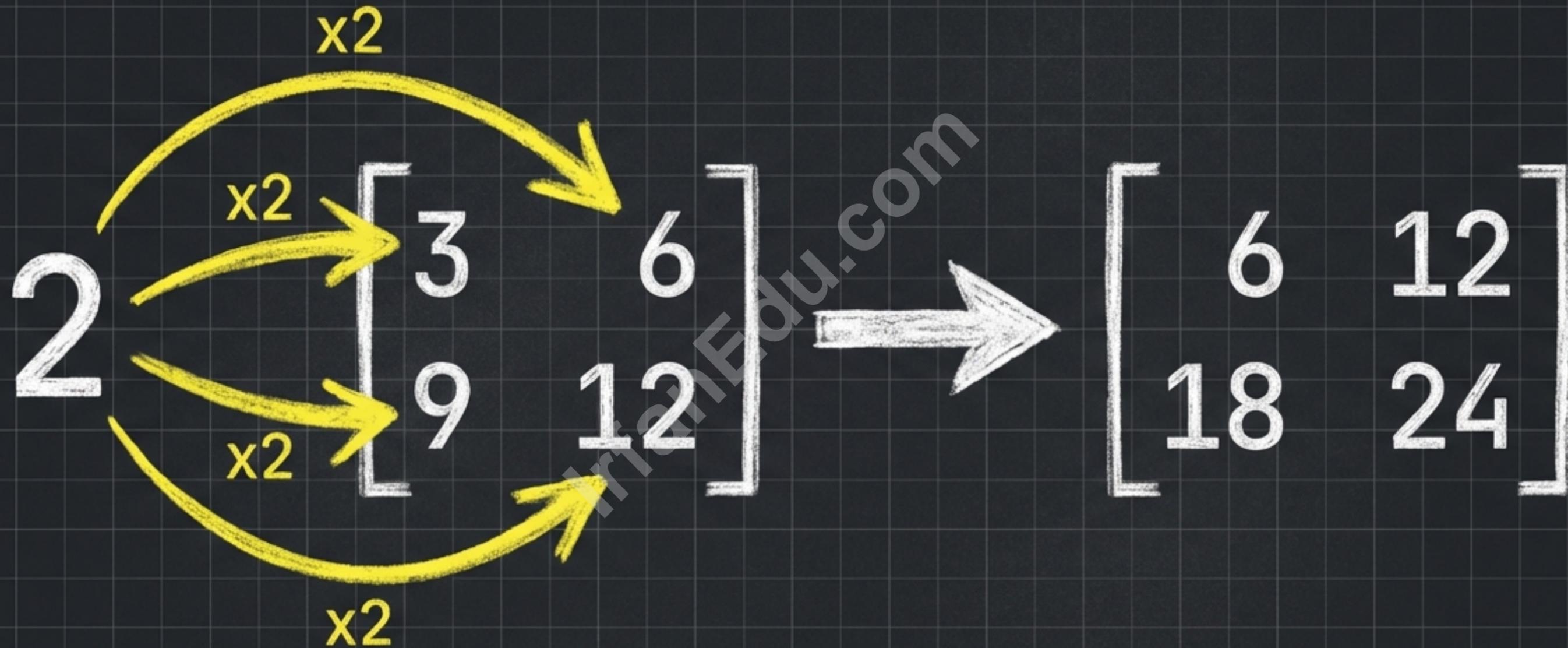
# COMBINING FORCES (ADDITION)



Dimensions Must Match Exactly



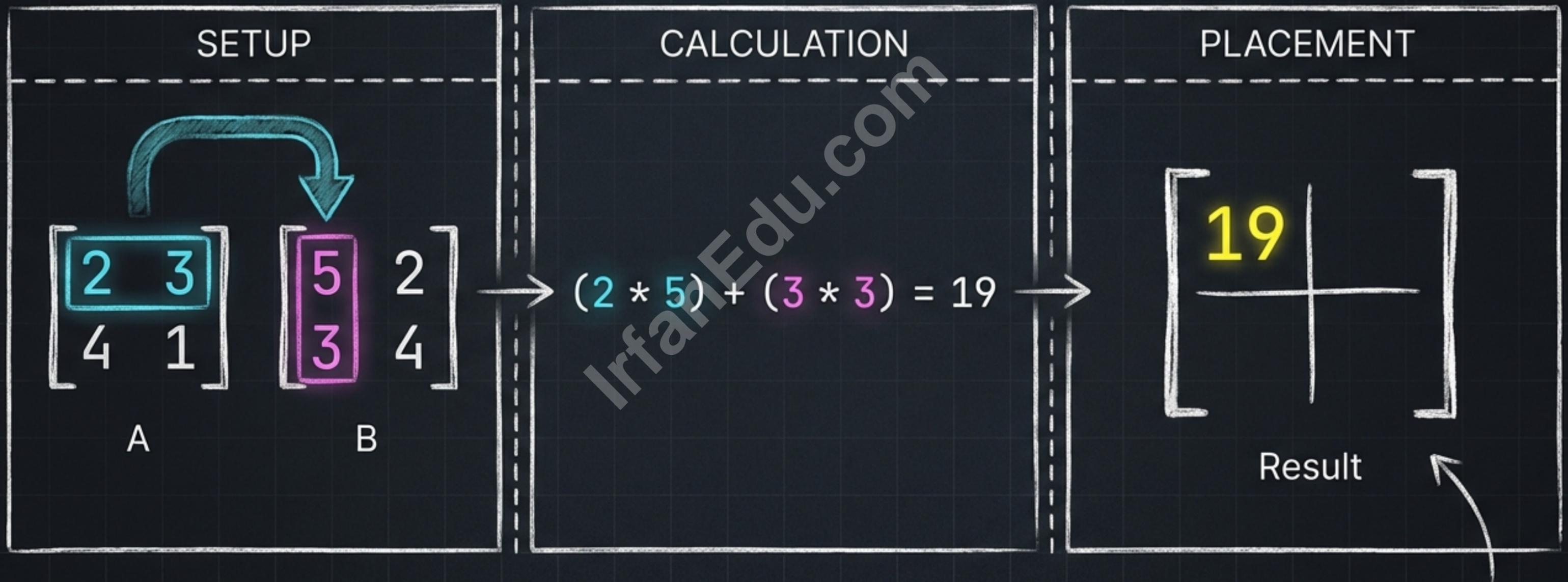
# SCALING THE SYSTEM



The scalar  $k$  distributes into every single cell like a flood fill.

# THE DOT PRODUCT MECHANISM

Row dives into Column



Repeat for every position.

# RULES OF ENGAGEMENT

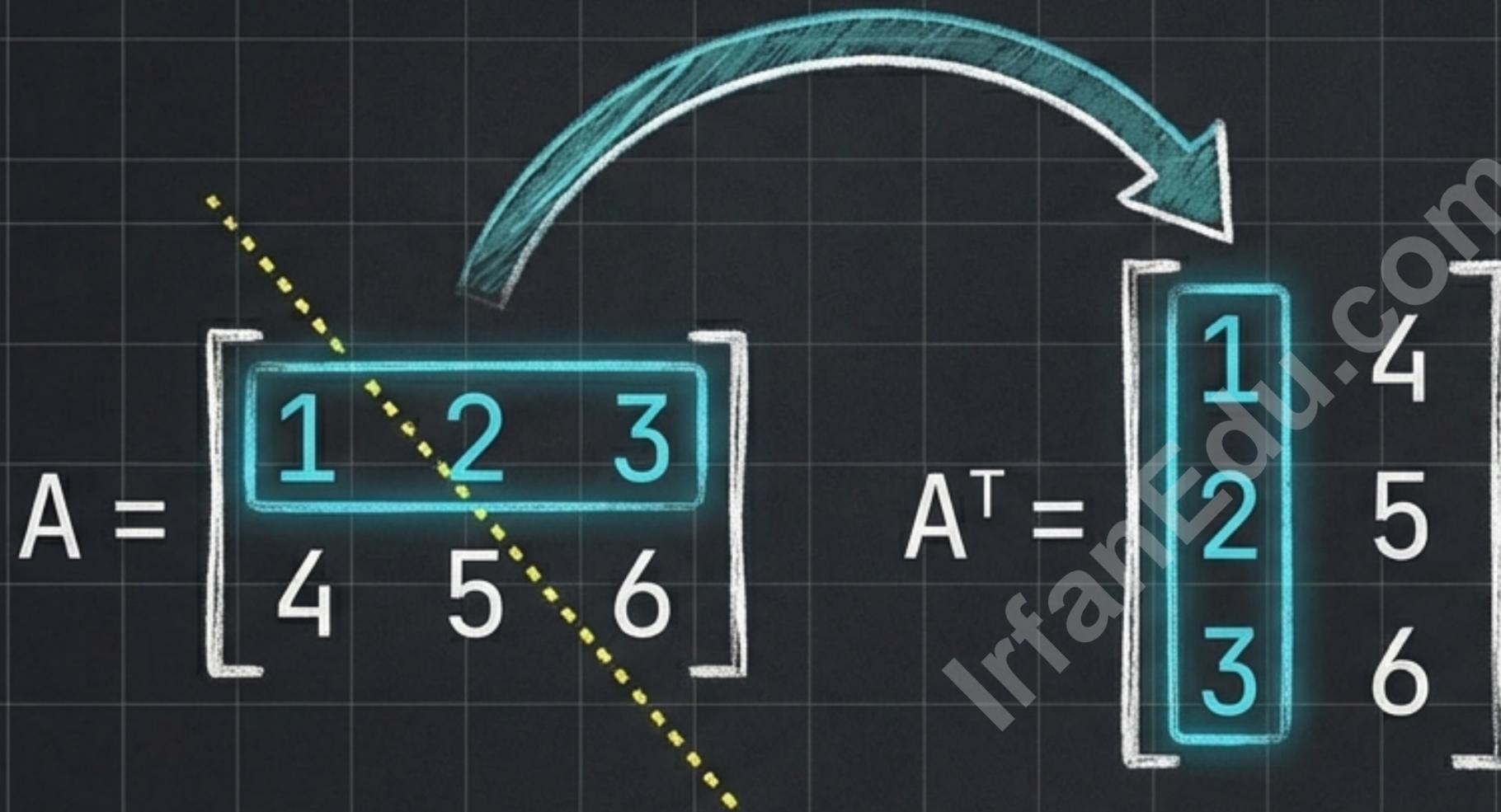
$$AB \neq BA$$

Matrix Multiplication is NOT Commutative. Order matters.



Associative Property DOES hold:  $(AB)C = A(BC)$

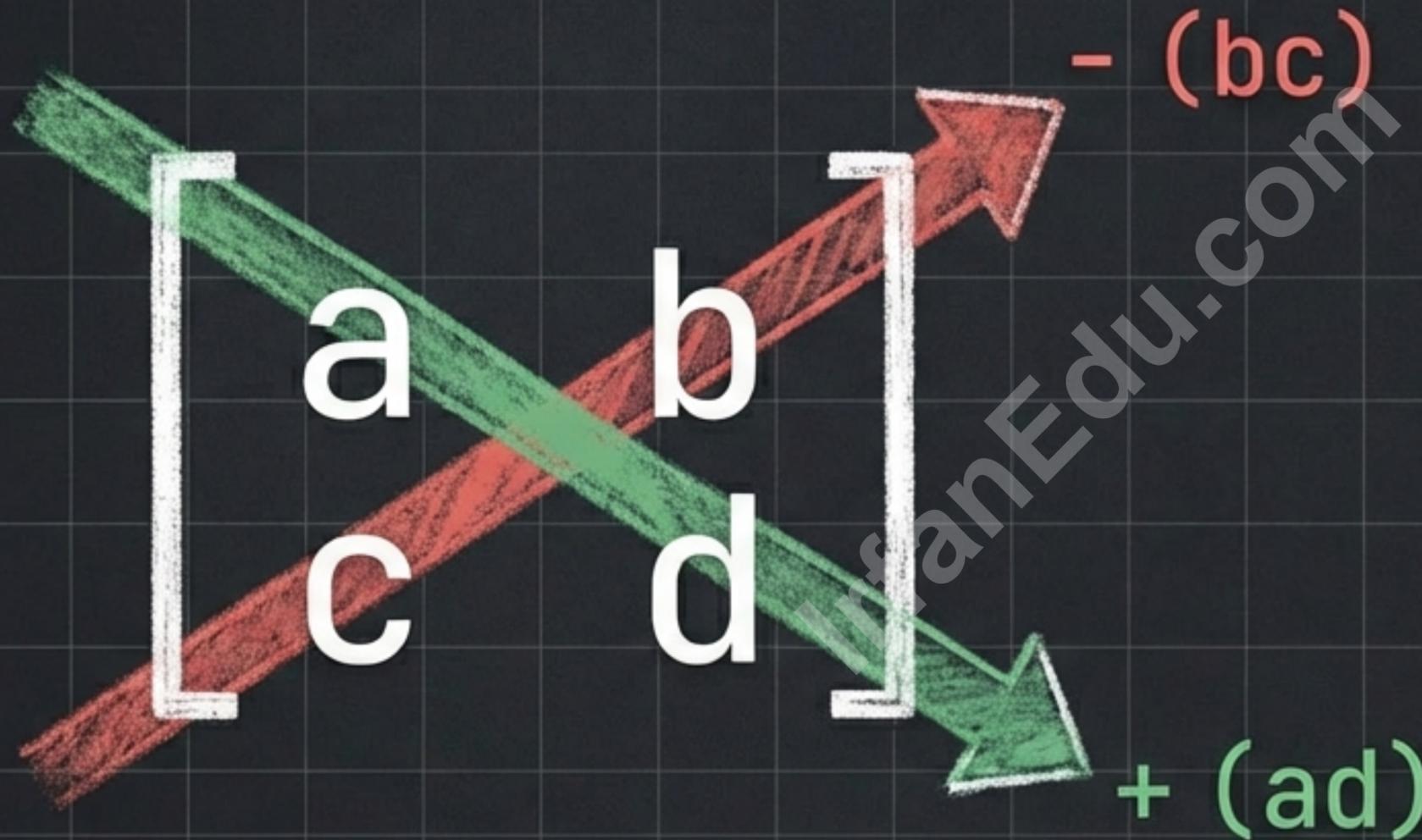
# THE MIRROR EFFECT (TRANSPOSE)



- Rows become Columns
- $(A^T)^T = A$
- Symmetric Matrix:  $A = A^T$

# THE DETERMINANT

The scalar DNA of a square matrix

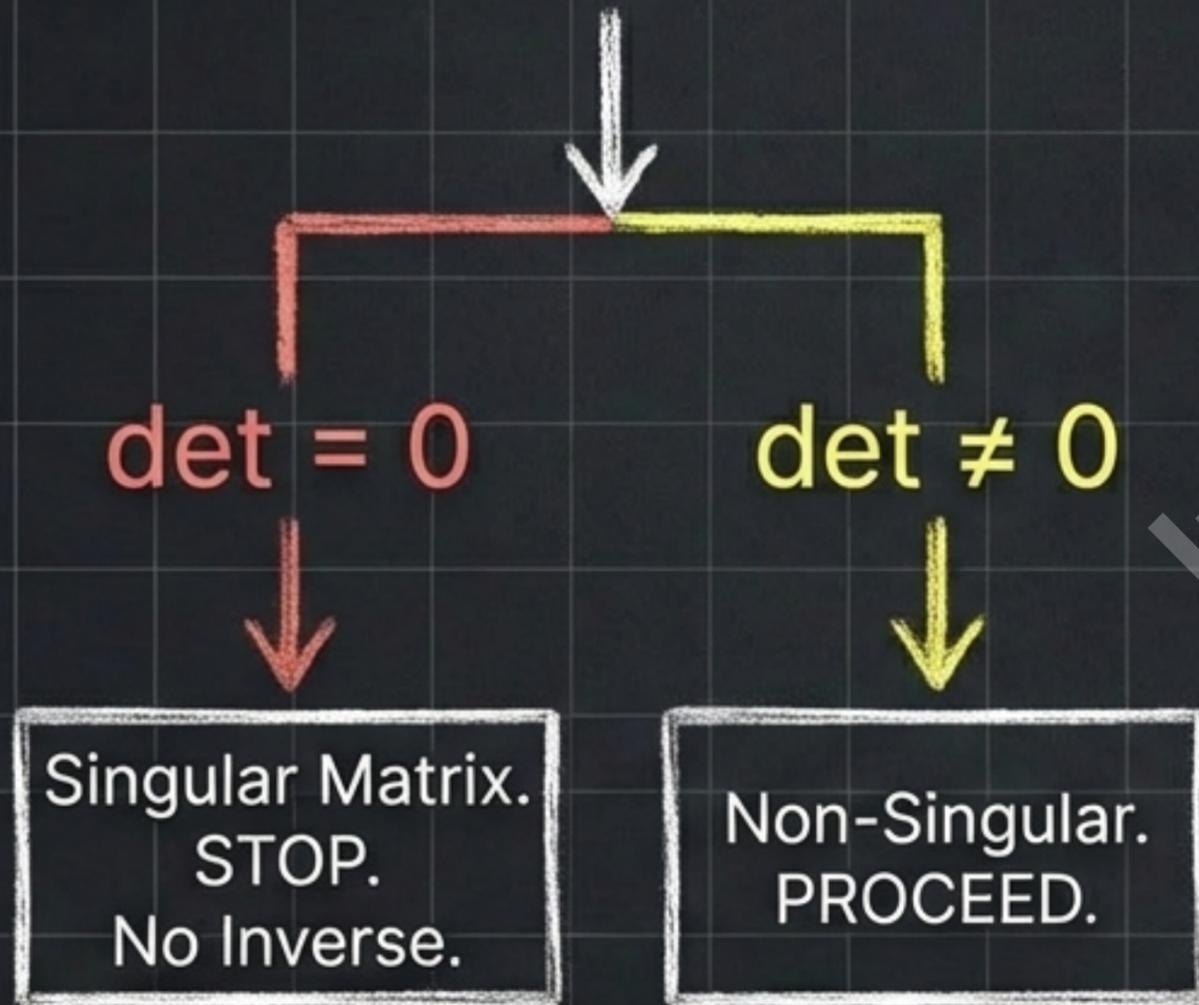


$$\det(A) = ad - bc$$

$$\begin{aligned} \det & \begin{vmatrix} 3 & 5 \\ 2 & 4 \end{vmatrix} \\ &= (3)(4) - (5)(2) \\ &= 12 - 10 = 2 \end{aligned}$$

# UNDOING THE MATRIX (THE INVERSE)

Calculate  
Determinant (det)



## The Formula for 2x2 Inverse.

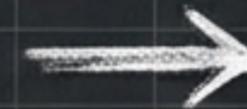
$$A^{-1} = \frac{1}{\det} * [\text{Adjoint Matrix}]$$

Original:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Adjoint:

The adjoint matrix is shown as  $\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ . Yellow curved arrows indicate the transformation: one arrow from 'd' to '-b' and another from '-c' to 'a', showing that the diagonal elements are swapped and the off-diagonal elements are negated.



# SOLVING LINEAR SYSTEMS

## Traditional Algebra

$$\begin{aligned}2x + 3y &= 8 \\4x + 1y &= 10\end{aligned}$$

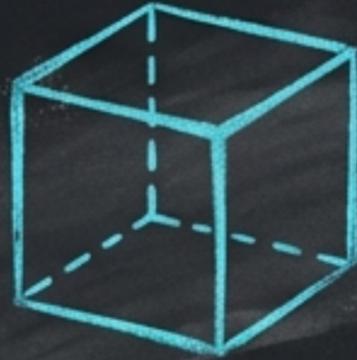
## Matrix Notation ( $AX = B$ )

$$\begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 8 \\ 10 \end{bmatrix}$$

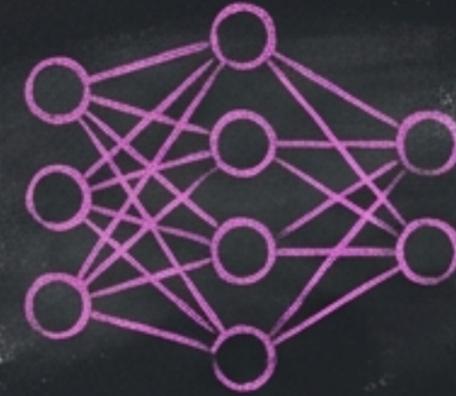
$$X = A^{-1} * B$$

Multiplication by inverse replaces division.

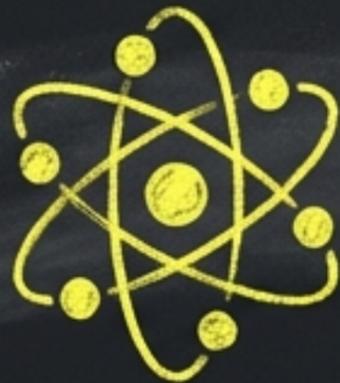
# THE ENGINE OF MODERN TECH



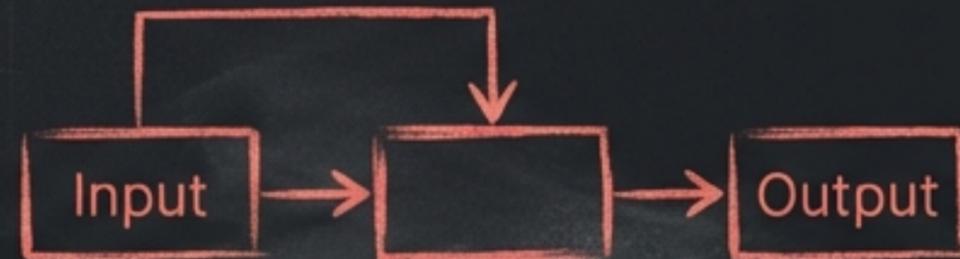
Matrices transform and rotate  
3D coordinates.



Weights and inputs processed via  
massive matrix multiplication.



Representing quantum states  
and operators.



Input-output models for  
industry analysis.

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# AVOID THESE TRAPS

## THE COMMUTATIVE ASSUMPTION

Thinking  $AB = BA$ .

## DIMENSION MISMATCH

Multiplying  $(2 \times 2)$  by  $(3 \times 2)$ .

## INDEX CONFUSION

Mixing up row/column order.

## THE SINGULAR TRAP

Inverting when Determinant is 0.

**PRO TIP** Always multiply your inverse by the original matrix to verify you get Identity (I).

$$\cancel{AB = BA}$$

$(2 \times 2)$  by  $(3 \times 2)$

← NO MATCH

~~$a_{col, row}$~~   
→  $a_{row, col}$

UNDEFINED ⚠

$1/0$

# TEST YOUR MASTERY

Find A + B

$$\begin{bmatrix} 5 & 2 \\ 3 & 7 \end{bmatrix} + \begin{bmatrix} 1 & 4 \\ 6 & 2 \end{bmatrix}$$

Calculate 3A

$$3 \cdot \begin{bmatrix} 2 & -1 \\ 4 & 5 \end{bmatrix}$$

Find Determinant

$$\begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$$

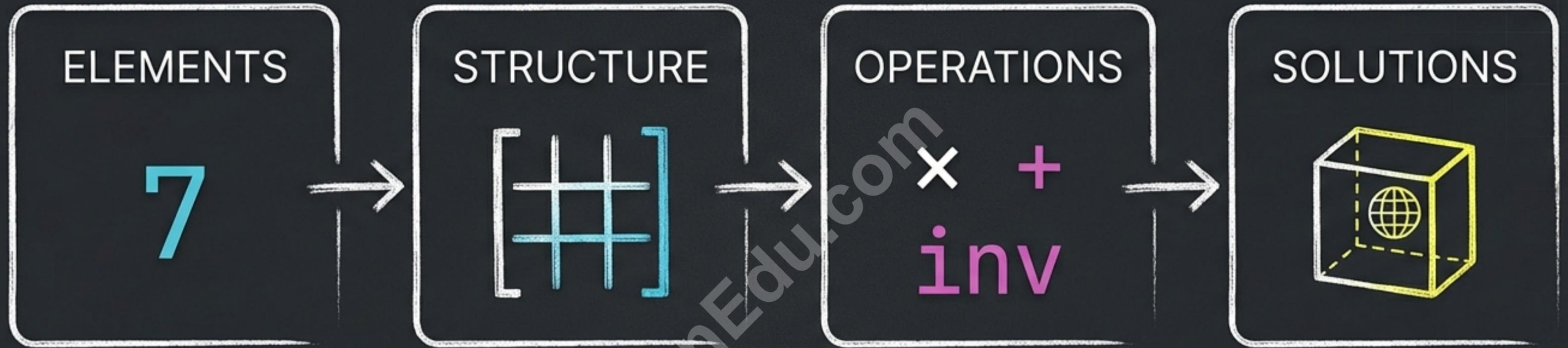
Find Inverse

$$\begin{bmatrix} 2 & 1 \\ 5 & 3 \end{bmatrix}$$

**ANSWERS:**

1.  $\begin{bmatrix} 6 & 6 \\ 9 & 9 \end{bmatrix}$
2.  $\begin{bmatrix} 6 & -3 \\ 12 & 15 \end{bmatrix}$
3. 2
4.  $\begin{bmatrix} 3 & -1 \\ -5 & 2 \end{bmatrix}$

# THE UNIVERSAL LANGUAGE



*“Mastering matrices is about seeing the structure behind the data. Whether in physics, AI, or engineering, the grid is the foundation.”*

Keep practicing. Verify dimensions. Trust the logic.